

# System Modeling in Time and Frequency Domains Part II

## Introduction

- In this brief chapter I continue to develop system modeling concepts started in Chapter 3
- To be clear, electronic circuit design needs are motivated by system level requirements, that is a receiver design is required to *perform in such a way*
- At the system level design requirements can be given in terms of *time domain* and *frequency domain* characterizations
- The mathematics of system modeling gets quite complex, but is also very powerful<sup>1</sup>
- In this chapter the math will be very light, mostly pictures
- The idea is to motivate the needs/requirements of particular circuit designs

## AM and FM Signal Modeling

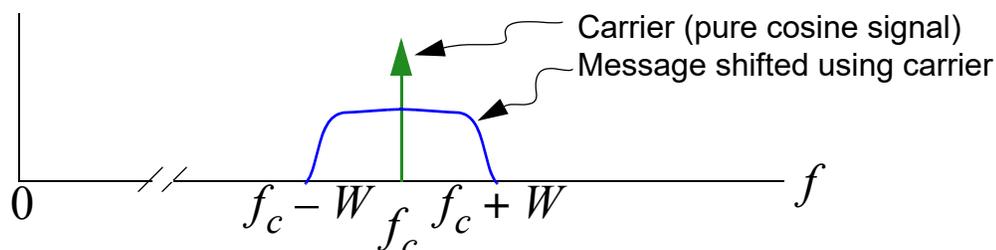
Here I provide details on AM and FM signal generation, which by the way, is a capability of the Analog Discovery

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1. M. Wickert, *Signals and Systems for Dummies*, Wiley, 2013.

## Mathematical Details of Amplitude Modulation

- The spectrum of an AM signal is shown below:



- An amplitude modulated signal is formed by combining a *message signal*  $m(t)$  together with a carrier signal  $c(t)$

$$\begin{aligned} x_{\text{AM}}(t) &= [A + m(t)]c(t) \\ &= A_c [1 + am_n(t)] \cos(2\pi f_c t) \end{aligned} \quad (5.1)$$

where

- $0 \leq a \leq 1$  defines what is known as the *modulation index*
- $f_c$  is the carrier frequency in Hz, typically much greater than the highest frequency found in  $m(t)$
- $m_n(t) = m(t)/|\min m(t)|$ , which insures that the smallest value of  $m_n(t)$  is  $-1$

### Example 5.1: Single Tone Modulation

- Let  $m(t) = m_n(t) = \cos(2\pi f_m t)$  where  $f_m = 5 \text{ kHz}$  and set the carrier frequency to  $f_c = 1 \text{ MHz}$
- The waveform in mathematical terms is

$$x_{\text{AM}}(t) = A_c [1 + a \cos(2\pi(5000)t)] \cos(2\pi \cdot 10^6 t) \quad (5.2)$$

- In communications signal processing the trig identity

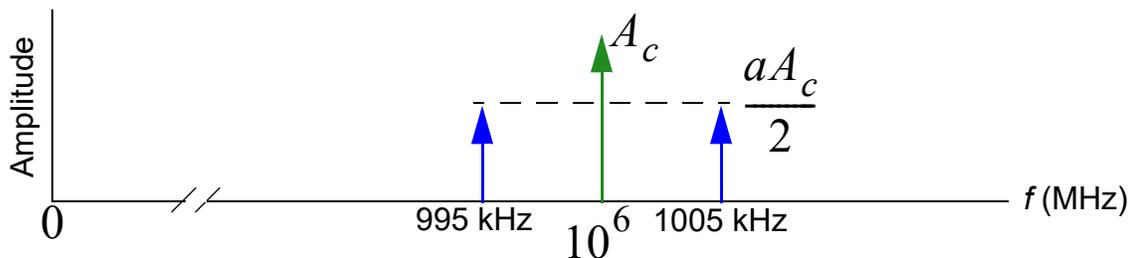
$$\cos(\theta)\cos(\phi) = \frac{1}{2}[\cos(\theta + \phi) + \cos(\theta - \phi)] \quad (5.3)$$

is used frequently!

- Making use of (5.3) to simplify (5.2) fully breaks down AM for a single tone message into three tones:

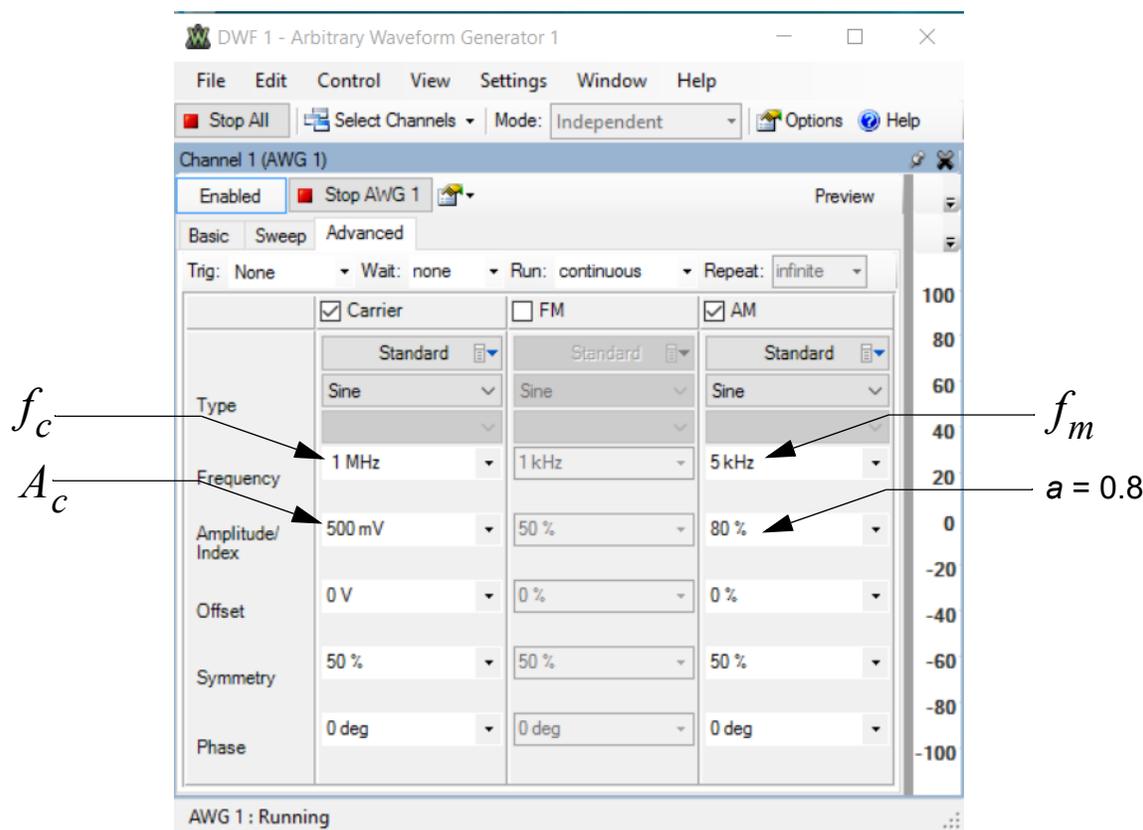
$$\begin{aligned} x_{AM}(t) = & \frac{A_c}{2}[\cos(2\pi(10^6 + 5000)t) \\ & + \cos(2\pi(10^6 - 5000)t)] \\ & + A_c \cos(2\pi \cdot 10^6 t) \end{aligned} \quad (5.4)$$

- The single-sided theoretical spectrum thus takes the form:

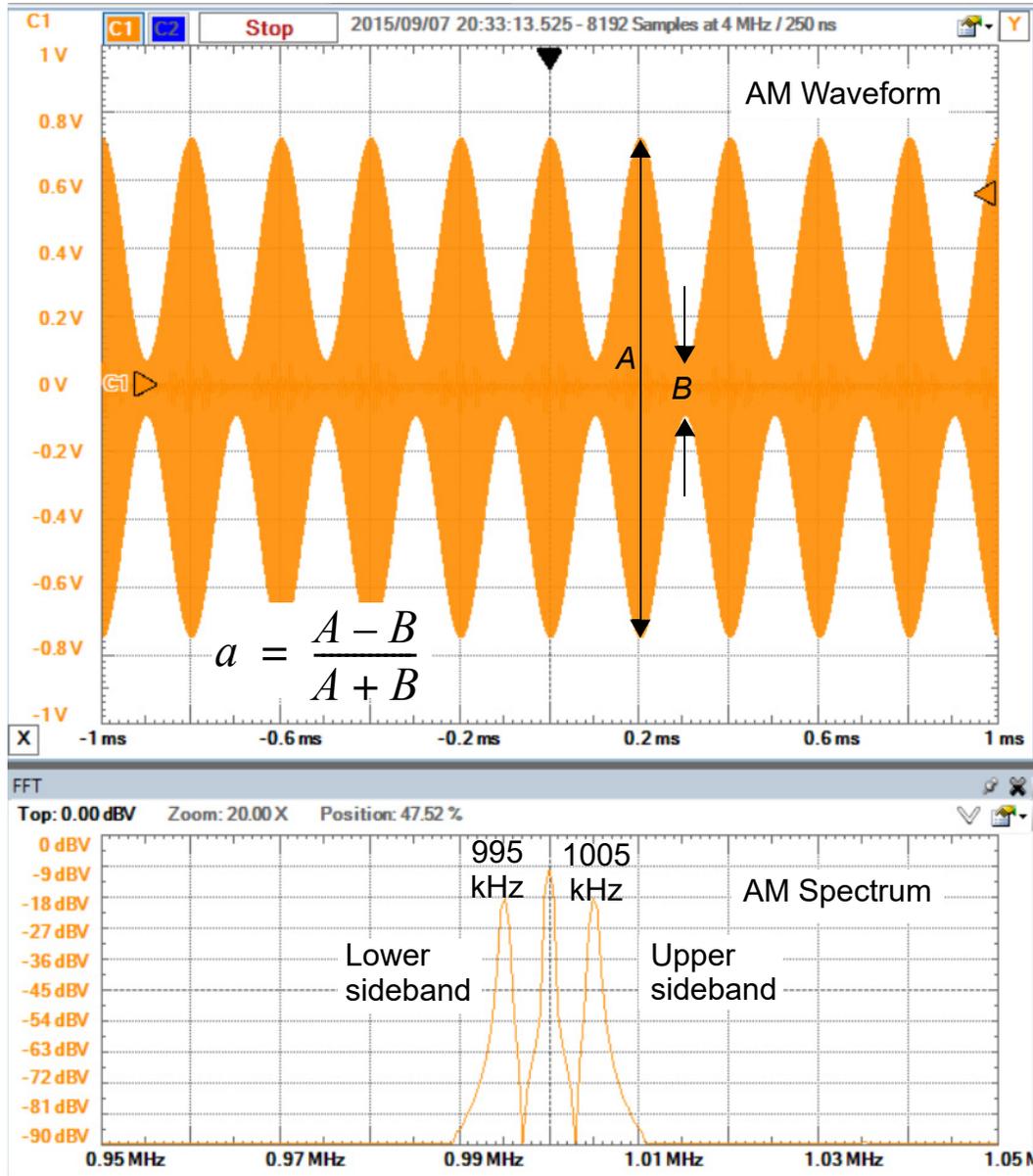


- The center tone or spectral line is due to just the carrier signal
- The spectral lines either side of the carrier are referred to as the *upper* (1005 kHz) and lower (995 kHz) sidebands
- Further note that the sidebands are at least 6 dB below the carrier spectral line; why? {if  $a = 1$  you have  $20\log_{10}(2)$  as the factor}

- Using the Analog Discovery you can create this waveform using the Arbitrary Waveform Generator



- **Note:** There are additional parameters that may be set to create an AM waveform, but for this example the above noted values are of primary importance
- When viewed on the scope with the FFT spectrum analyzer turned on you observe the following:



- **Note:** For the case of single tone modulation the modulation index,  $a$ , controls the relative strength of the upper and lower sidebands

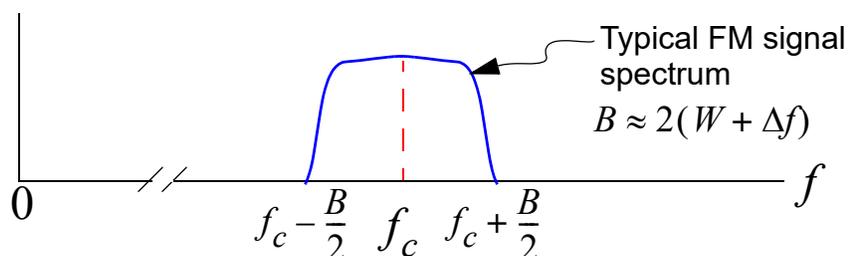
- The sidebands should be down

$$-20\log_{10}(0.8/2) = 7.96 \text{ dB} \quad (5.5)$$

- The time domain peak-to-peak ( $A$ ) and valley-to-valley ( $B$ ) measurements also directly relate to  $a$

## Mathematical Details of Frequency Modulation

- The spectrum of an FM signal is shown below:



- An FM signal is formed by making the instantaneous frequency of the carrier sinusoidal signal vary with the amplitude of the message signal  $m(t)$
- In mathematical terms this is represented as

$$x_{\text{FM}}(t) = A_c \cos \left[ 2\pi f_c t + 2\pi f_d \int_{-\infty}^t m(\beta) d\beta \right] \quad (5.6)$$

where

- $A_c$  is the carrier amplitude ( $A_c^2/2$  is the power of the transmitted FM signal)
- $m(t)$  is the message signal (just as in AM)
- $f_d$  is the frequency deviation constant (how much frequency variation for a given  $m(t)$ )
- For those with a calculus background, yes there is an integral in this expression
- The instantaneous frequency,  $f_{\text{inst}}(t)$ , is  $1/(2\pi)$  times the derivative of the cosine argument, making

$$\begin{aligned}
 f_{\text{inst}}(t) &= \frac{1}{2\pi} \cdot \frac{d}{dt} \left[ 2\pi f_c t + 2\pi f_d \int_{-\infty}^t m(\beta) d\beta \right] \\
 &= f_c + f_d m(t)
 \end{aligned} \tag{5.7}$$

- The last line of (5.7) is what matters here!
- The instantaneous frequency of FM signal  $x_{\text{FM}}(t)$  moves about  $f_c$  according to  $f_d m(t)$

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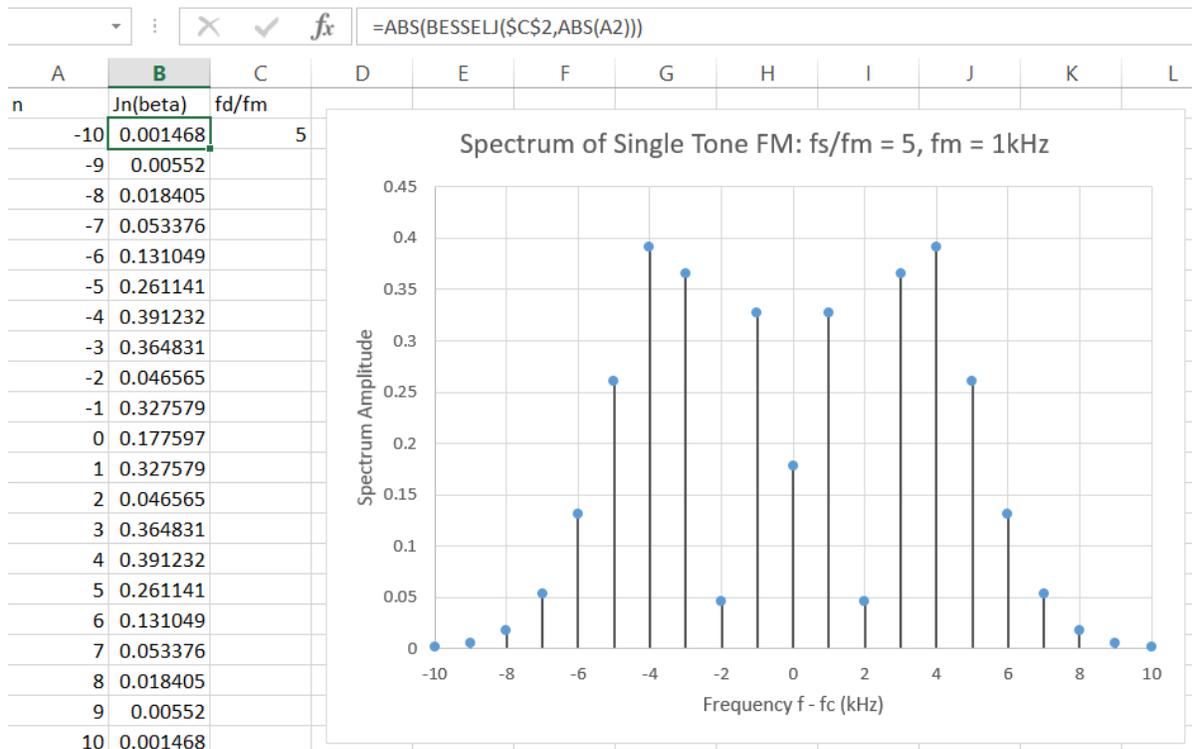
### Example 5.2: Single Tone Modulation

- Let  $m(t) = \cos(2\pi f_m t)$  where  $f_m = 5$  kHz and set the carrier frequency to  $f_c = 1$  MHz
- The waveform in Mathematical terms is

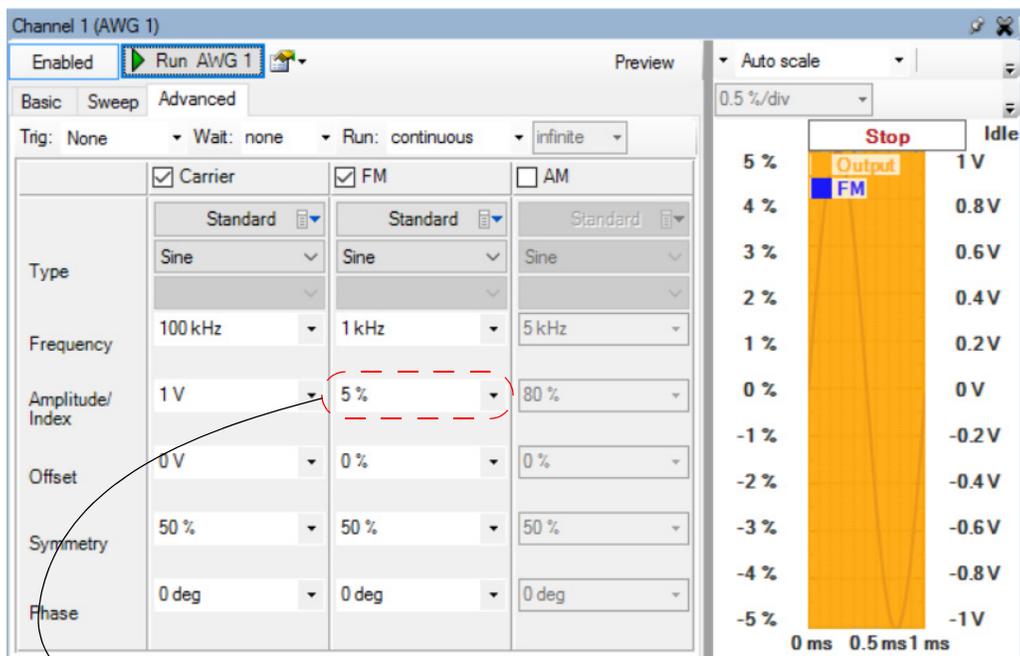
$$\begin{aligned}
 x_{\text{FM}}(t) &= A_c \cos \left[ 2\pi \cdot 10^6 t + \frac{f_d}{f_m} \sin(2\pi f_m t) \right] \\
 &= A_c \sum_{n=-\infty}^{\infty} J_n(\beta) \cos(2\pi f_c t + 2\pi n f_m)
 \end{aligned} \tag{5.8}$$

where  $J_n(\beta)$  is a *Bessel function* (a special function in mathematics) and  $\beta = f_d/f_m$  is known as the modulation index for single tone FM

- You can use Excel (or Python, Mathematica, MATLAB) to make a spectrum plot

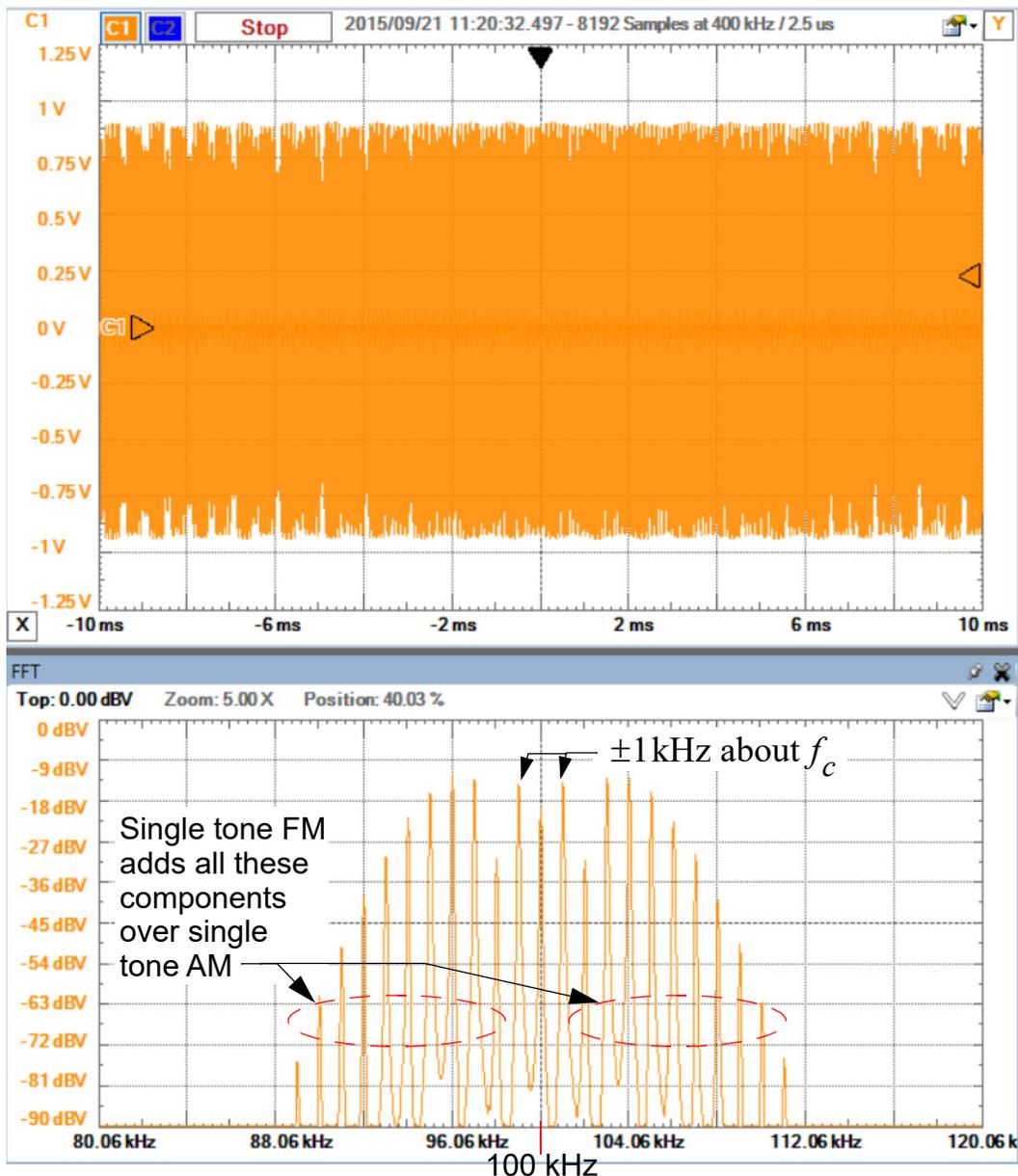


- Using the Analog Discovery this waveform can be created using the AWG



The peak deviation is percent of the carrier frequency, here 100 kHz, so for  $f_d/f_m = 5$  requires  $f_d = 5$  kHz or 5%

- Next observe the measured (FFT) spectrum using the scope



- The results look, taking into account the dB scaled used here versus the linear scale in the Excel plot
- The takeaway from this example is that with FM the occupied bandwidth easily exceeds the bandwidth of the message signal; the bandwidth is now about  $2(1+5)k = 12$  kHz!

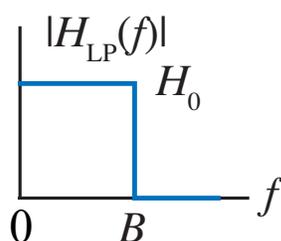
## System Modeling

- With signal time and frequency domain in hand, it is now time to take a look at some system modeling
- The goal is to look at simple system level modeling as it applies to radio receiver design
- Systems operate on one or more signal inputs to produce a new/modified output signal

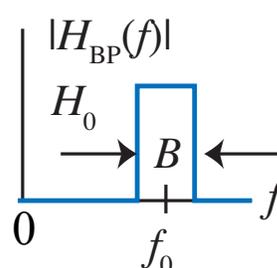
### Filters

- A filter is a system that removes undesired signal content
  - Think of a coffee filter or water filter
  - The filter removes the unwanted and lets the wanted pass
- The filter *frequency response* of the filter is key concept here
- Consider ideal lowpass and bandpass filters:

Lowpass Filter (LPF)



Bandpass Filter (BPF)

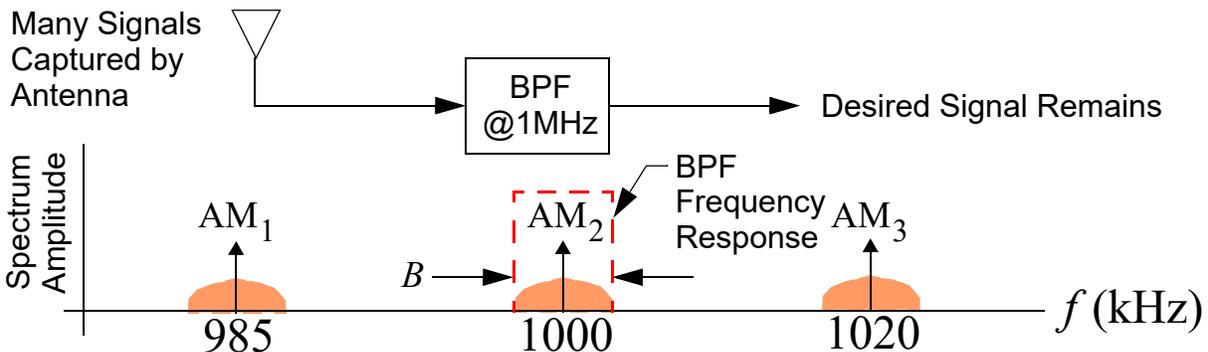


- Both types are essential in receiver design
- When multiple received signals are present how do you select the desired signal? **Answer:** Use a filter!

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**Example 5.3: Dealing with Multiple Received Signals**

- Consider the following received signals at the input to an AM radio receiver



- To receiver the signal at 985 kHz requires a re-tuning of the BPF from 1000 kHz to 985 kHz
  - This design approach is the basis for the *tuned radio frequency* (TRF) AM receiver<sup>1</sup>
  - In practice changing the center frequency of a filter and providing a narrow bandwidth  $B$ , is a design challenge
  - There are design alternatives
- 
- Using LTspice it is possible to create a behavioral model of both lowpass and bandpass filters
  - The basic idea involves representing the filter mathematically as a ratio of polynomials in the  $s$ -domain
    - What is the  $s$ -domain?
    - For realizable filters, those that can be build using actual

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1. [https://en.wikipedia.org/wiki/Tuned\\_radio\\_frequency\\_receiver](https://en.wikipedia.org/wiki/Tuned_radio_frequency_receiver)

circuit elements, the  $s$ -domain representation is the *system function* [1],  $H(s)$ , where

$$H(s) = \frac{b_M s^M + b_{M-1} s^{M-1} + \dots + b_1 s + b_0}{a_N s^N + a_{N-1} s^{N-1} + \dots + a_1 s + a_0} \quad (5.9)$$

$N$  is the filter order,  $M \leq N$ , and  $s$  is a complex variable, meaning it has both real and imaginary parts (e.g.,  $s = \sigma + j2\pi f$ )

- The filter frequency response is obtained from the system function by letting  $s = j2\pi f$ , where  $j = \sqrt{-1}$
- By using LTspice you can keep the detailed mathematics to a minimum
- Consider a popular class of filter known as *Butterworth*, having LPF system functions for  $N = 1, 2, 3$  of the form

$$H_1^{\text{BU}}(s) = \frac{\omega_c}{\omega_c + s}, \omega_c 2\pi f_c$$

$$H_2^{\text{BU}}(s) = \frac{\omega_c^2}{s^2 + \sqrt{2}\omega_c s + \omega_c^2} \quad (5.10)$$

$$H_3^{\text{BU}}(s) = \frac{\omega_c^3}{s^3 + 2\omega_c s^2 + 2\omega_c^2 s + \omega_c^3}$$

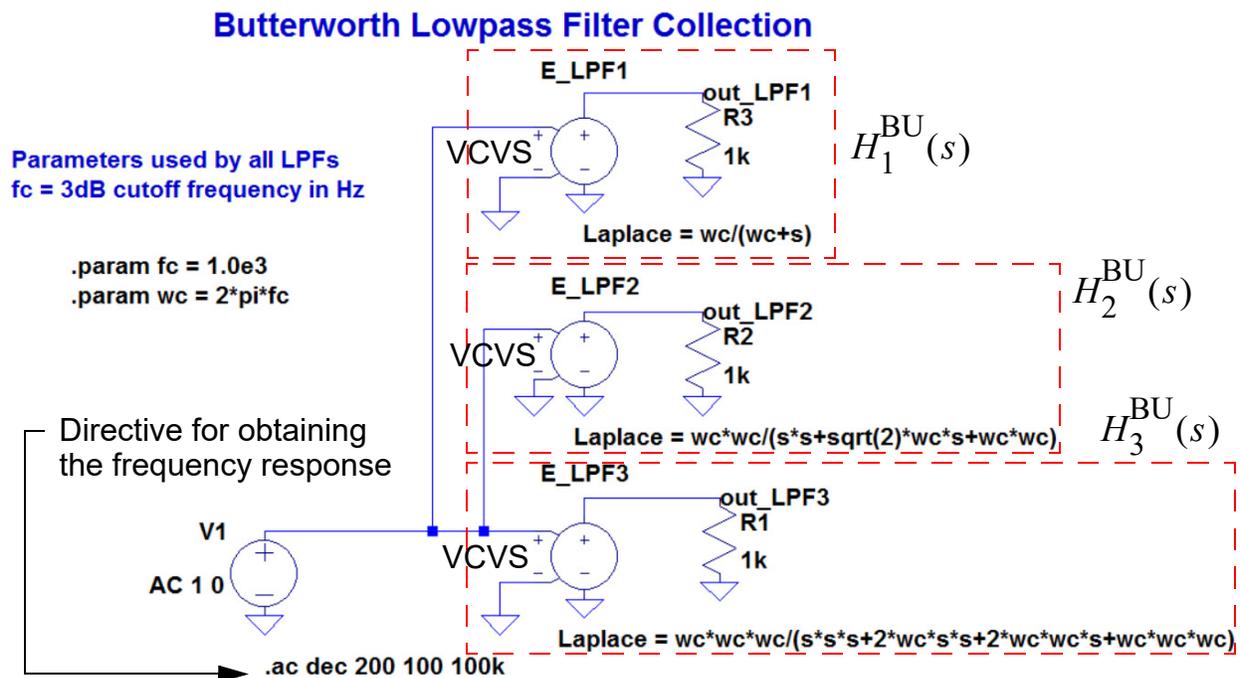
- The BPF version of the above is obtained by making the algebraic substitution

$$\frac{s}{\omega_c} \rightarrow \frac{\omega_o}{\Delta\omega} \left( \frac{s}{\omega_o} + \frac{\omega_o}{s} \right) = Q \left( \frac{s}{\omega_o} + \frac{\omega_o}{s} \right) \quad (5.11)$$

where  $\omega_o$  is the filter center frequency,  $\Delta\omega$  is the 3dB bandwidth of the filter in rad/s (divide by  $2\pi$  to obtain  $\Delta f$  in Hz), and  $Q$  is the filter *quality factor*

### Example 5.4: A Collection LPF Filters in LTspice

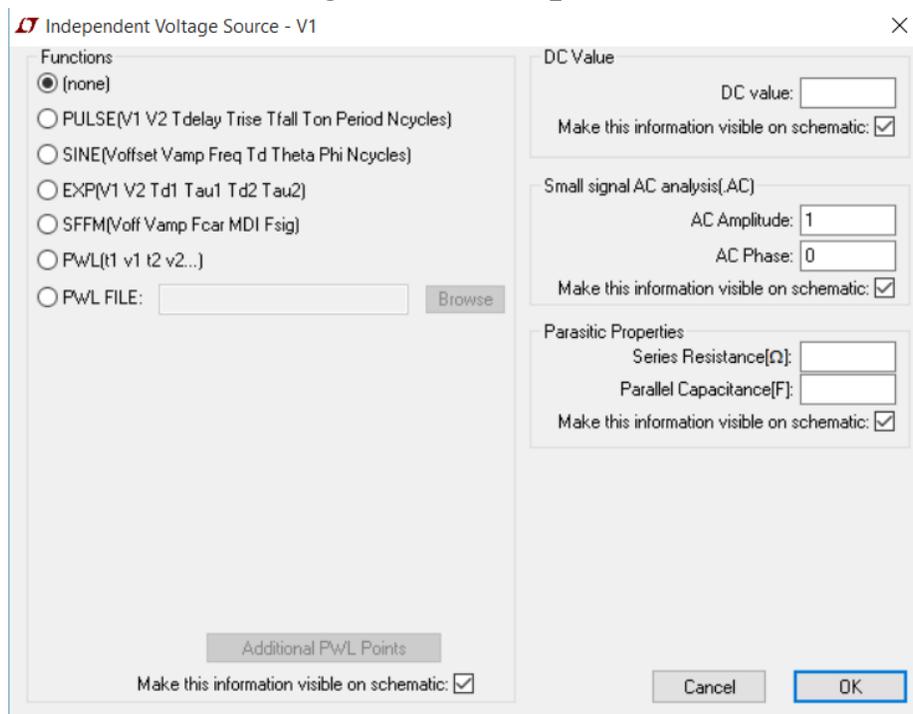
- The three lowpass filters of (5.10) are implemented in the schematic shown below



- The key to direct implementation these filters is the voltage controlled voltage source (VCVS) and the *Laplace* statement found inside the VCVS model
  - Laplace comes from *Laplace transform*, which is an integral transform for transforming time domain signals and

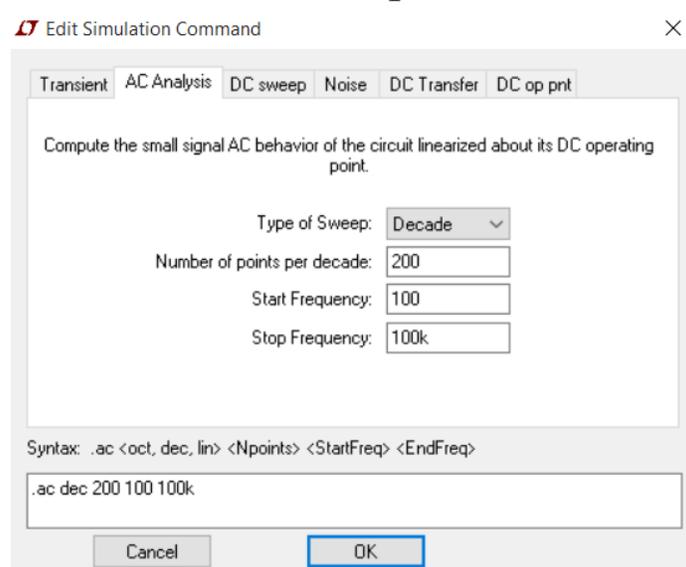
systems to their  $s$ -domain counter parts [1]

- To obtain the frequency response of a filter you replace the `.tran` directive with the `.ac` directive
- The details of setting an AC simulation involve two steps:
- **Step 1:** Set the AC signal source parameters



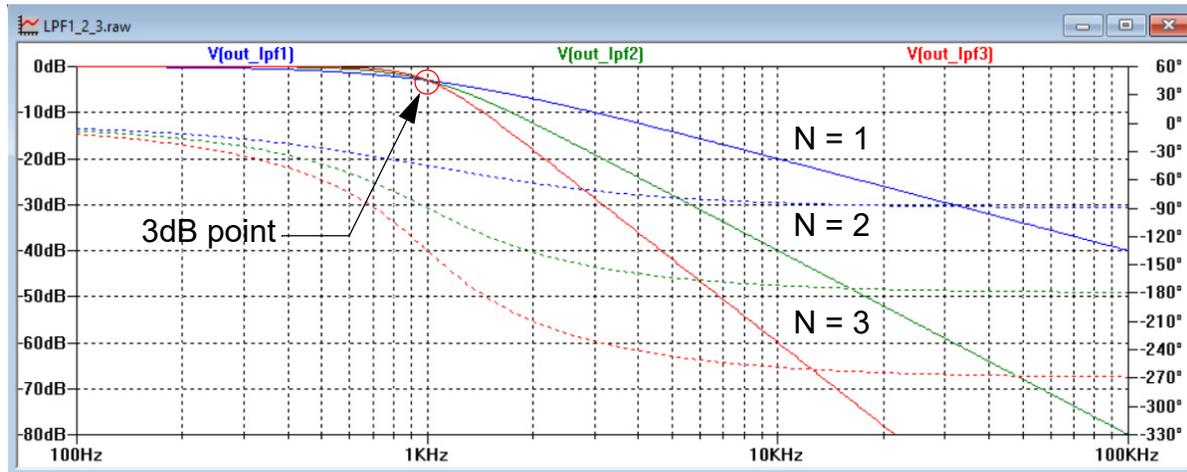
Set the AC source values

- **Step 2:** Set the AC simulation parameters



Final directive for schematic

- The frequency response plot is obtained after running the simulation



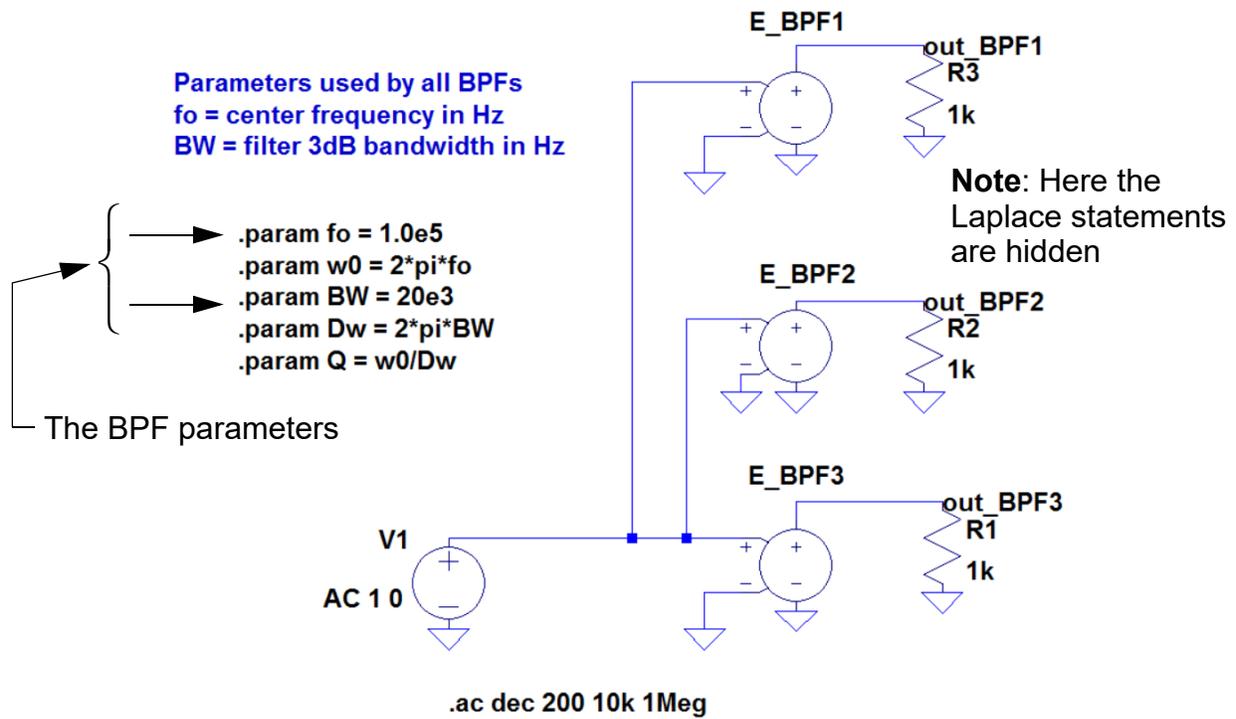
- **Note:** Here  $f_c = 1 \text{ kHz}$  for all three filters
- The solid line is the filter voltage gain in dB and the dashed line (right axis) is the phase shift the filter introduces at a give frequency
- This LTspice example also introduces the directive `.param` which allows you schematic to contain variables

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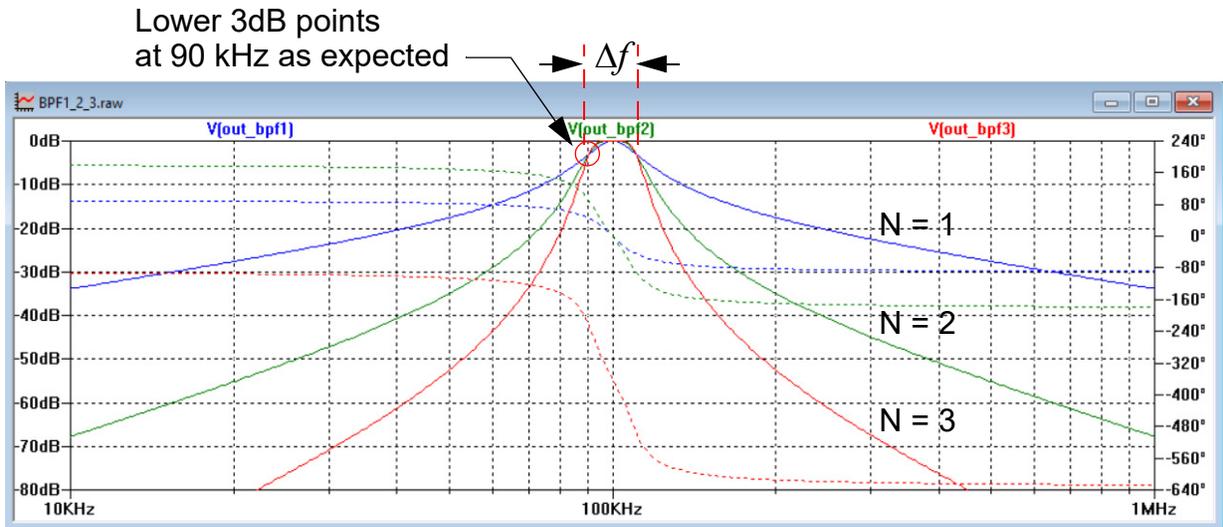
### Example 5.5: A Collection of BPF Filters in LTspice

- This example is a rework of the LPF example using the transformation of (5.11)
- The controlling parameters reflect the attributes of a BPF, that is center frequency  $\omega_o = 2\pi f_o$  and bandwidth  $\Delta\omega = 2\pi\Delta f$

### Butterworth Bandpass Filter Collection



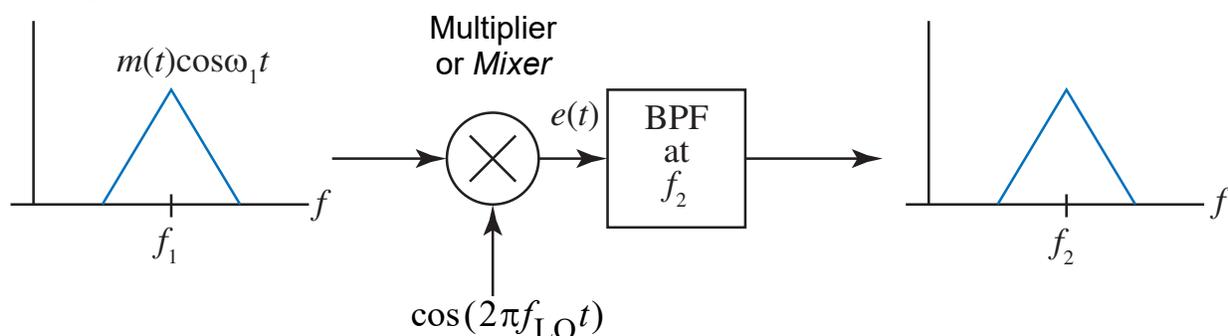
- The sweep range is different to accommodate the BPF centered at 100 kHz and bandwidth of 20 kHz



- Again both the magnitude in dB and phase is plotted
- Because of the transformation properties, the filter order is effectively doubled, i.e.,  $N = 2$  LPF implies  $N = 4$  BPF

## Frequency Translation and Mixing

- Frequency translation is moving signals from one center frequency to another



- To accomplish this you multiply (mix) the input signal with  $\cos(2\pi f_{LO}t)$  to produce a new signal,  $e(t)$
- The mixing action reduces down to the trig identity of (5.3), which says that  $e(t)$  will consist of two signals, one centered at  $|f_1 - f_{LO}|$  and the other centered at  $|f_1 + f_{LO}|$ 
  - One of the two signals is retained and the other is rejected by using a BPF (see the block diagram)
- So how do you choose the local oscillator (LO) frequency  $f_{LO}$ ?
  - The LO can sit above at  $|f_1 + f_2|$  or below at  $|f_1 - f_2|$

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### Example 5.6: Translation to 455 kHz

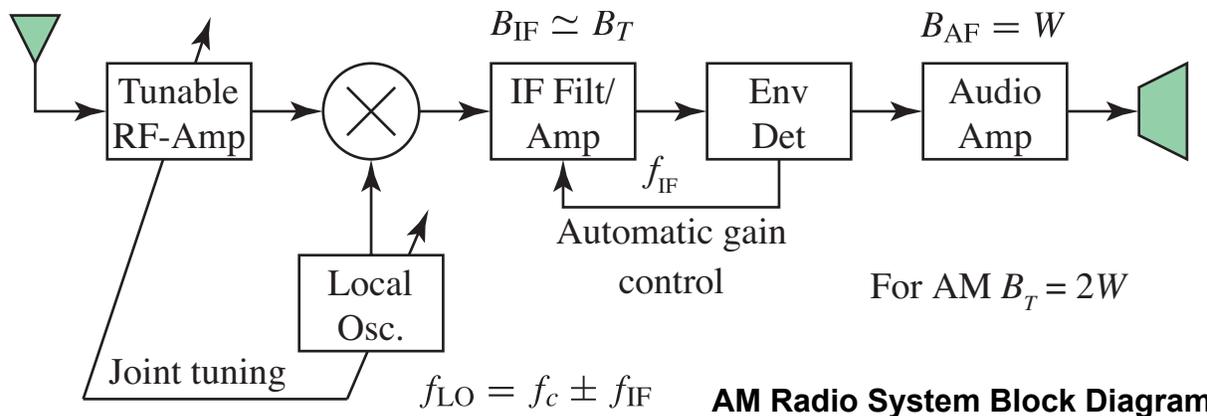
- In the design of an AM *superheterodyne* receiver<sup>1</sup>  $f_2$  is referred to as the *intermediate frequency* (IF)
- In the AM radio kit you will assemble,  $f_2 = f_{IF} = 455$  kHz

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1. [https://en.wikipedia.org/wiki/Superheterodyne\\_receiver](https://en.wikipedia.org/wiki/Superheterodyne_receiver)

- To receive a signal at 1000 KHz you can choose  $f_{LO}$  to be either  $1000 + 455 = 1455$  kHz or  $1000 - 455 = 545$  kHz

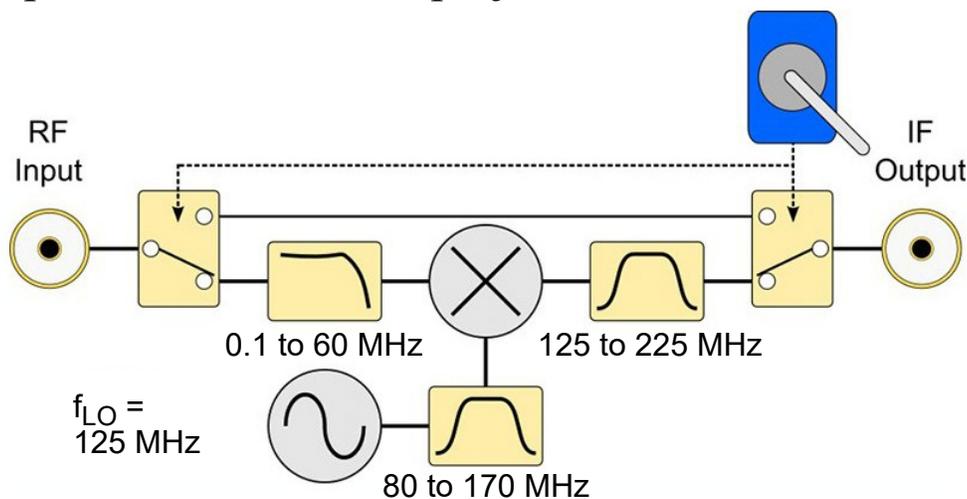
$$2f_{IF} > B_{RF} > B_T$$



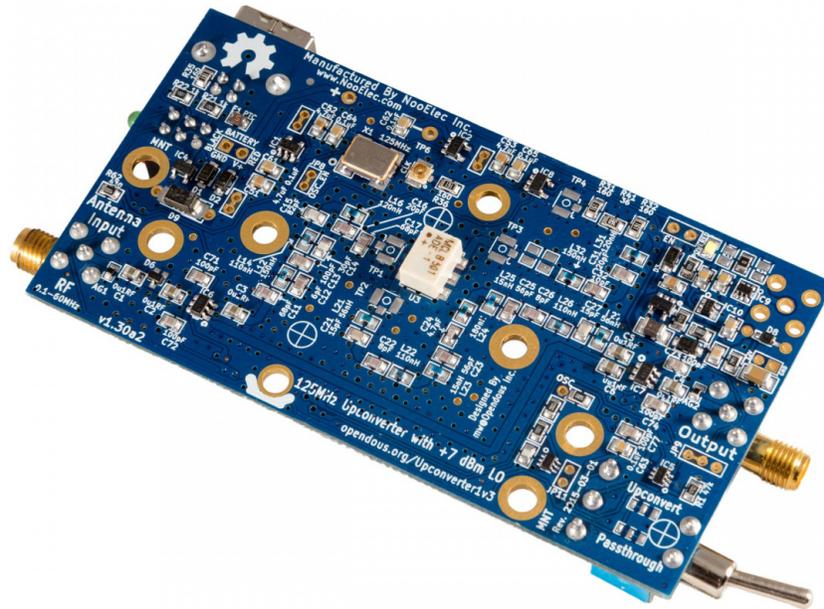
- The block diagram shows additional elements that are needed to make a superhetro receiver
  - Amplifiers (three different types shown)
  - Envelope detector

### Example 5.7: Ham-It Up Upconverter

- An open source hardware project for the RTL-SDR

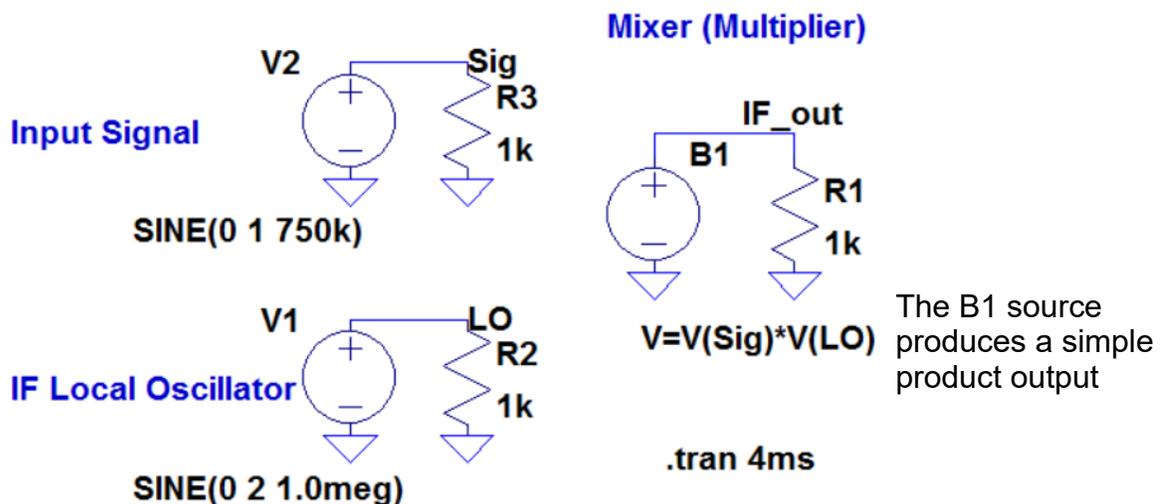


- The completed design:



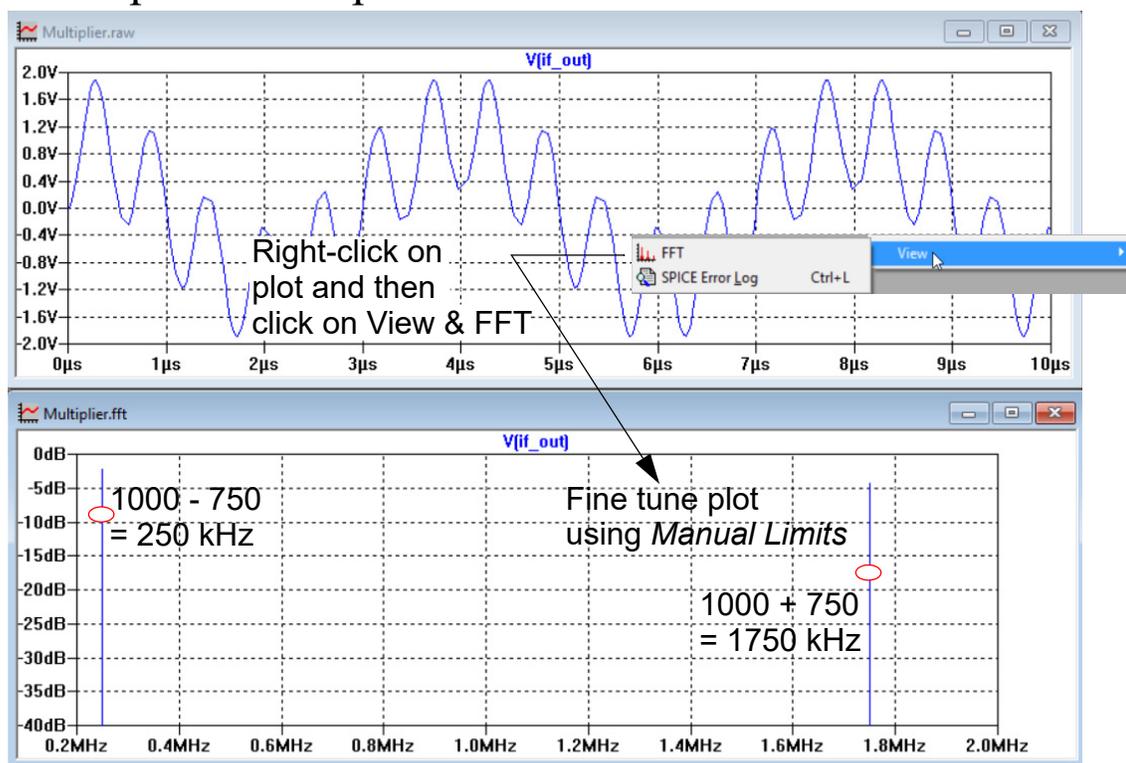
### Example 5.8: Multiplier in LTspice

- Again using LTspice behavioral modeling, in this case the B-source, you can process waveforms using mathematical functions, such as simply multiplying two signals together



- Here the inputs are sinusoids at 750 kHz and 1000 KHz

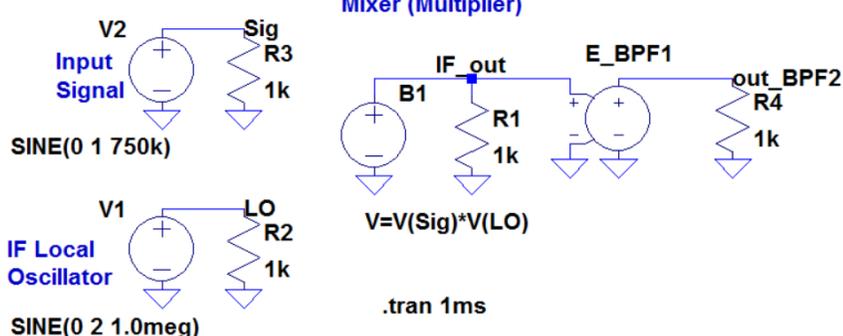
- You expect the output to be sinusoids at  $1000 \pm 750$  kHz



- If you add a BPF centered at 250 kHz to the out you expect just the 250 kHz signal to remain, right!

Parameters used by all BPFs  
 $f_o$  = center frequency in Hz  
 $BW$  = filter 3dB bandwidth in Hz

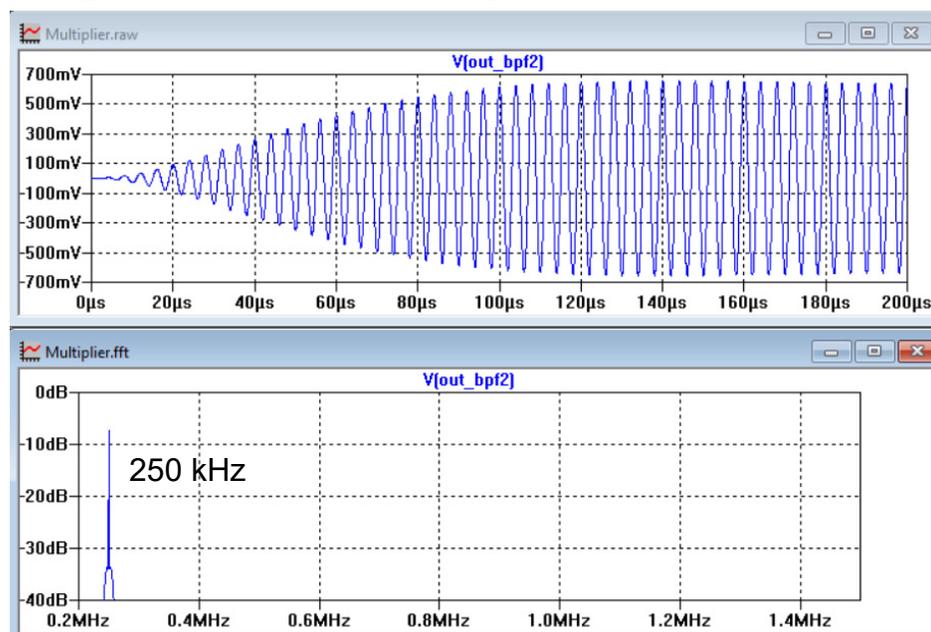
```
.param fo = 250e3
.param w0 = 2*pi*fo
.param BW = 10e3
.param Dw = 2*pi*BW
.param Q = w0/Dw
```



- To add the BPF I copy one filter (BPF2) from the Butterworth BPF collection schematic
  - **Warning:** The filter makes the simulation run very slowly
- I then set filter parameters accordingly, here I set  $f_o = 250$  kHz and  $\Delta f = 10$  kHz

- The time and spectra at the BPF output

The filter charges up and produces a pure tone at 250 kHz



## Gain Stages

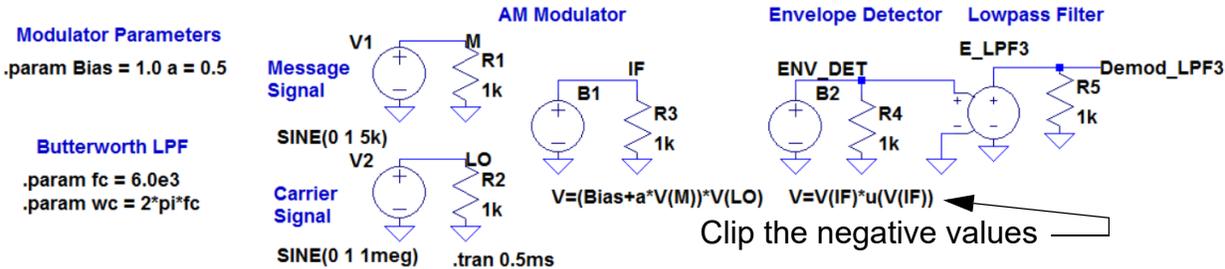
- The gain stages that you see in Example 5.4 are critical to the receiver design
- Amplifier circuits are needed
  - Radio frequency (RF) amplification at the receiver front end insure that the weak received signal is brought to a useful signal level
  - The IF stage of a receiver generally very high gain, but needs to be adjustable so that strong signals will not overload processing blocks downstream
  - The audio amplifier is needed to drive speakers or earbuds, which is not so much of a voltage gain issue, but the ability of the amplifier to drive a low resistance (impedance) load, e.g., 8 or 16 ohms

### Demodulation

- A received and frequency translated radio signal needs to undergo *demodulation*, which is the undoing of the modulation found at the transmitter
  - Once the signal is demodulated it is ready to move to the audio amplifier
- It seems obvious that demodulation depends on the modulation type
  - AM demodulation is often accomplished with an *envelope detector*
  - Demodulation of FM requires a *frequency discriminator*

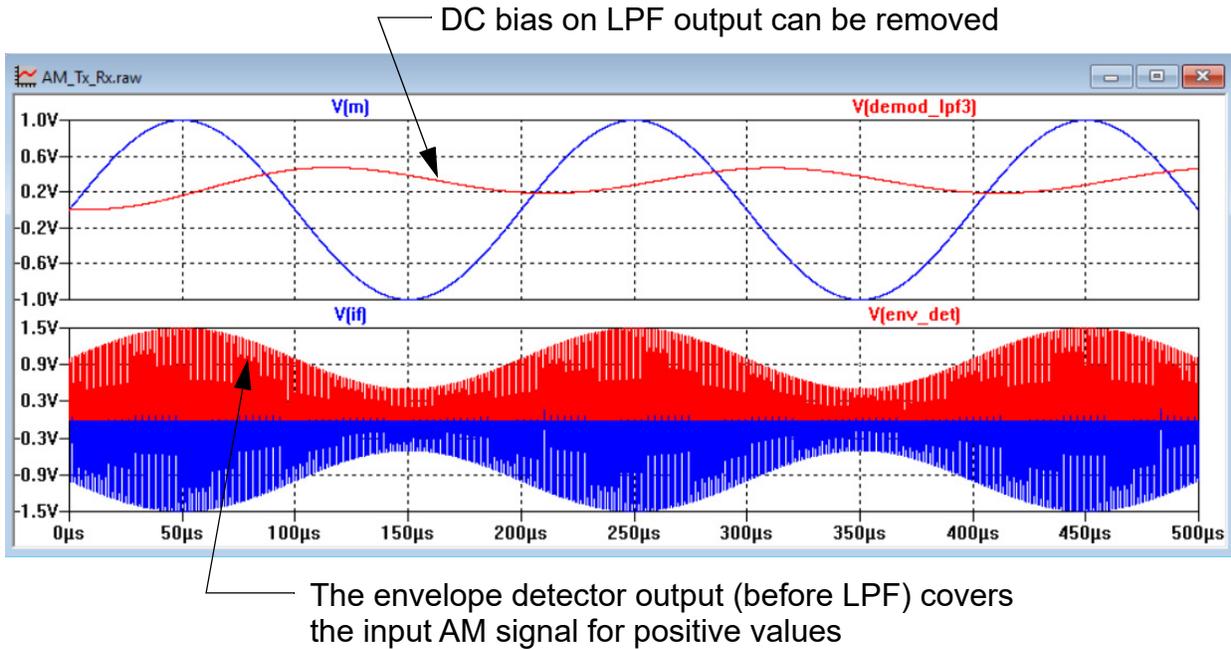
#### Example 5.9: LTspice Ideal Envelope Detector

- Using the B-source you simulate an ideal envelope detector
- To get started however a source of AM is needed and that can be created using another B-source model
- A lowpass filter thrown on the end of the processing chain will recover the original message (here a 5 kHz tone)

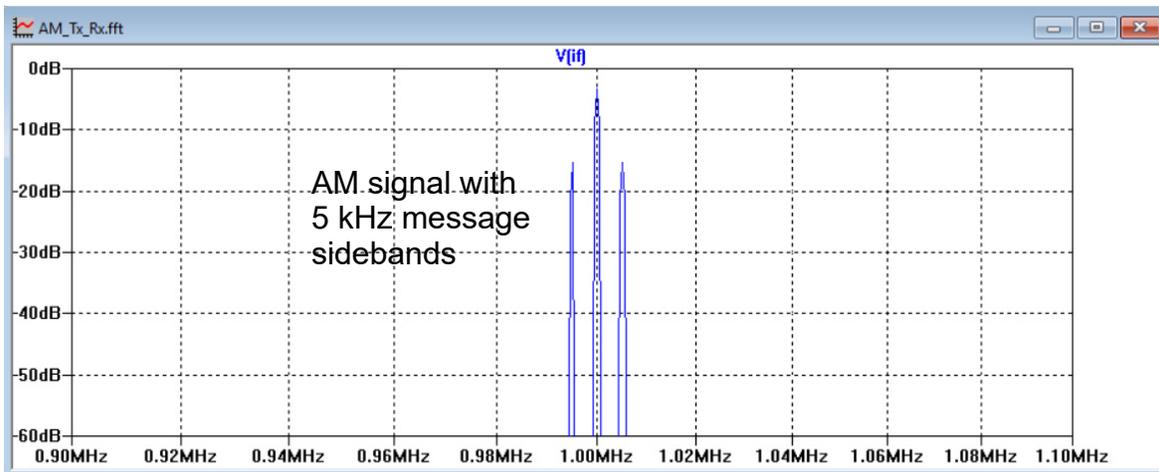


- Note:  $\pi = \text{pi}$  is defined by LTspice
- The ENV\_DET B-source returns the positive values or zero

- The outputs taken at four test points:

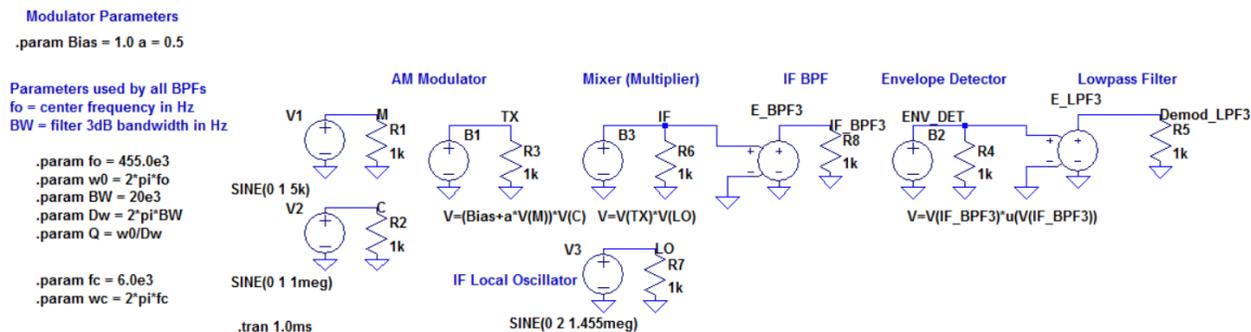


- Looking at the LTspice FFT spectra you should see upper and lower sidebands at 5 kHz relative to the 1 MHz carrier



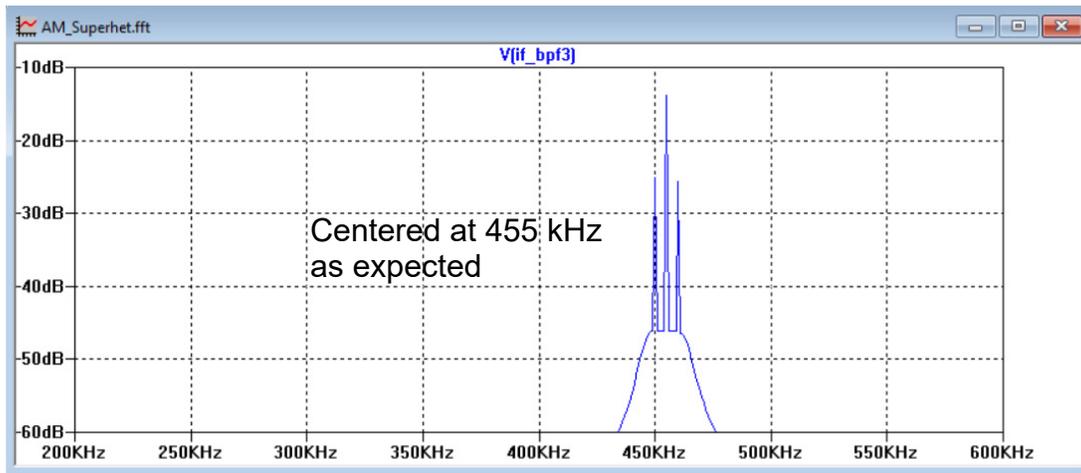
## AM Superheterodyne Transceiver Simulation

- A complete AM transceiver system simulation can be build using LTspice

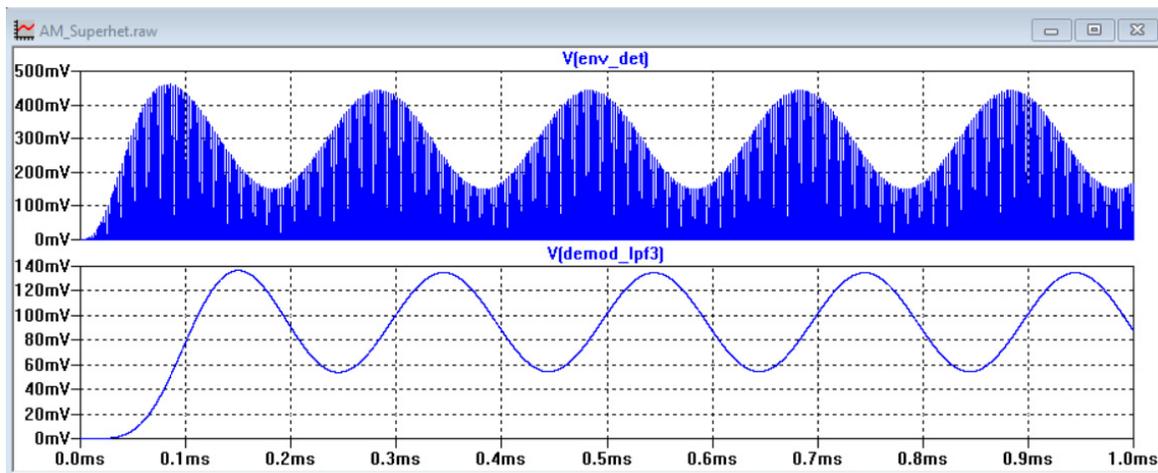


- In the schematic you can see the carrier is at 1 MHz
- The single tone message is at 5 kHz (modulation index  $a = 0.5$ )
- A 455 kHz IF is chosen, so to receiver the 1 MHz AM signal high-side LO tuning is chosen, which implies  $f_{\text{LO}} = 1.455 \text{ MHz}$
- The IF BPF filter bandwidth is set to 20 kHz ( $\pm 10 \text{ kHz}$ )
- The post envelope detector LPF cutoff is set to 6 kHz
- Output time domain waveforms and frequency domain spectra can be shown at various test points

- Consider first the AM spectrum at the IF filter output



- The envelope detector output, before and after the LPF



## References

- [1] M. Wickert, *Signals and Systems for Dummies*, Wiley, 2013.